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Nom d 'utilisateur PC : phil
Nom de l'ordinateur : PORTABLE2

Version logiciel : 1.0.0.0

The diagram shows a mechanism with 8 links and 4 joints. The links are numbered 1 through 8. Link 1 is the fixed frame. Link 2 is a horizontal link. Link 3 is a horizontal link. Link 4 is a vertical link. Link 5 is a vertical link. Link 6 is a horizontal link. Link 7 is a horizontal link. Link 8 is a horizontal link. The joints are labeled A, B, C, and D. Joint A is a revolute joint between links 2 and 3. Joint B is a revolute joint between links 3 and 4. Joint C is a revolute joint between links 4 and 5. Joint D is a revolute joint between links 5 and 6. The mechanism is shown in a state where the links are in a specific configuration. The joints are labeled A, B, C, and D. The links are numbered 1 through 8. The diagram is a schematic representation of a mechanism with 8 links and 4 joints.

Cotes paramètres :

Repères de points :

Repères de pièces d'entités :

Rep	Entité	Description	5	segment	Bielle
1	segment	Corps	6	segment	Palonier
2	segment	Piston	7	segment	Bielle
3	segment	Bielle	8	segment	Dépouille
4	segment	Volant d'inertie			